

Construction of a copula estimator through recursive partitioning of the unit hypercube

O. Laverny ^{1,2} V. Maume-Deschamps ¹ E. Masiello ¹ D. Rullière ¹

March 31, 2020

¹ Université Lyon 1

² SCOR SE

Table of contents

1. Introduction
2. Piecewise linear copulas
3. Recursive Estimation procedure
4. Asymptotic behavior
5. Bagging and cross-validation
6. Simulation Study
7. Conclusion

Introduction

Copulas Basics

Suppose that X is a (continuous) random vector of dimension d with c.d.f F and marginals c.d.f $(F_i)_{i \in \{1, \dots, d\}}$. Then Sklar's theorem [6] gives us the copula of X as :

$$C(u) = F(F_1^{-1}(u_1), \dots, F_d^{-1}(u_d))$$

- C is a c.d.f with uniform margins on $[0, 1]$.
- It characterises the dependence structure of F in the sense that F is completely characterised by C and the F_i 's.

The estimation of the copula is a wide-treated subject: there exists a lot of parametric distributions that can be fitted. Some non-parametric models exists but are facing problems in high dimensions.

Density estimation trees

In **regression**, the CART algorithm from Breiman [3] selects a covariate and a univariate breakpoint, minimizing a loss, and assign to each leaf the mean response inside the leaf.

In **density estimation**, the DET from Ram and Gray [4] selects a dimension and a breakpoint minimizing a loss, and assign to each leaf the *frequency of observations*:

$$f(x) = \sum_{\ell \in \mathcal{L}} \frac{f_{\ell}}{\lambda(\ell)} \mathbf{1}_{x \in \ell}$$

- What loss can we use ?
- Will this yield a copula if applied to pseudo-observations ?

Piecewise linear copulas

Definition

Let $\mathbb{I} = [0, 1]^d$ be the unit hypercube and \mathcal{L} a partition of \mathbb{I} .

Definition (Piecewise linear copula)

Let the piecewise linear copula be defined by its distribution function:

$$\forall u \in \mathbb{I}, C_{p, \mathcal{L}}(u) = \sum_{\ell \in \mathcal{L}} p_{\ell} \lambda_{\ell}(u)$$

- $\lambda_{\ell}(u) = \frac{\lambda([0, u] \cap \ell)}{\lambda(\ell)}$ where λ is the lebesgue measure.
- p is a vector of weights summing to one.

Corresponding density : $c_{p, \mathcal{L}}(u) = \sum_{\ell \in \mathcal{L}} \frac{p_{\ell}}{\lambda(\ell)} \mathbf{1}_{u \in \ell}$

Copula constraints

We restrict the leaves in \mathcal{L} to be hyperboxes of the form $[a, b]$.

Property (Copula constraints are linear in the weights)

$C_{p,\mathcal{L}}$ is a proper copula

\iff

$$p \in \mathcal{C}_{\mathcal{L}} = \{p \in \mathbb{R}^{|\mathcal{L}|} : Bp = g \text{ and } p \geq 0\}$$

$$B_1 = (\lambda_{\ell_i}(u_i))_{(i,u) \in \{1,\dots,d\} \times M_{\mathcal{L}}, \ell \in \mathcal{L}} \quad (\text{size } nd \times |\mathcal{L}|)$$

$$B_2 = (1)_{\ell \in \mathcal{L}} \quad (\text{size } 1 \times |\mathcal{L}|)$$

$$g_1 = (u_i)_{(i,u) \in \{1,\dots,d\} \times M_{\mathcal{L}}} \quad (\text{size } nd)$$

$$B = (B_1, B_2) \quad (\text{size } (nd + 1) \times |\mathcal{L}|)$$

$$g = (g_1, 1) \quad (\text{size } (nd + 1))$$

Where $M_{\mathcal{L}}$ is the set of middle-points of leaves in \mathcal{L} .

Kendall τ , Spearman ρ , Kendall d.f. K

Definition

$$\tau = 4 \int C(u) c(u) du - 1, \text{ and } \rho = 12 \int C(u) du - 3, \text{ and } K(t) = \mathbb{P}(C(U) \leq t)$$

Property (Piecewise linear class)

$$\tau = -1 + 2 \sum_{\substack{\ell \in \mathcal{L} \\ k \in \mathcal{L}}} \prod_{i=1}^d (b_i \wedge d_i - a_i \wedge c_i) (b_i \wedge d_i + a_i \wedge c_i - 2c_i) \\ + 2 (d_i - c_i) (b_i - a_i \wedge d_i)$$

$$\rho = -3 + 6 \sum_{\ell \in \mathcal{L}} p_\ell \prod_{i=1}^d (2 - b_i - a_i)$$

$$K(t) = \sum_{\ell \in \mathcal{L}} \frac{p_\ell}{\lambda(\ell)} \left(\gamma_+ \left(d, \frac{t - C(a)}{p_\ell} \right) \mathbf{1}_{\frac{t - C(a)}{p_\ell} \in [0, 1]} + \mathbf{1}_{\frac{t - C(a)}{p_\ell} > 1} \right)$$

where we denoted $\ell = (a, b]$ and $k = (c, d]$, \wedge denotes the minimum operator and γ_+ is the upper regularised gamma function.

Recursive Estimation procedure

An integrated square error loss...

We use the integrated square error between densities.

$$\begin{aligned}\|c_{p,\mathcal{L}} - c\|_2^2 &\approx \|c_{p,\mathcal{L}}\|_2^2 - 2 \langle c_{p,\mathcal{L}}, c \rangle && \text{(additive indep.)} \\ &\approx \|c_{p,\mathcal{L}}\|_2^2 - \frac{2}{n} \sum_{i=1}^n c_{p,\mathcal{L}}(u_i) && \text{(MC plug-in)} \\ &= \sum_{\ell \in \mathcal{L}} \frac{p_\ell^2}{\lambda(\ell)} - 2 \sum_{\ell \in \mathcal{L}} \frac{p_\ell f_\ell}{\lambda(\ell)} && \text{(f = emp. freq)} \\ &= p' A p - 2 p' A f && \text{(A = diag}(\lambda(\ell)^{-1}\text{)} \\ &= \|p\|_{\mathcal{L}}^2 - 2 \langle p, f \rangle_{\mathcal{L}}\end{aligned}$$

Where $\langle x, y \rangle_{\mathcal{L}} = \sum_{\ell \in \mathcal{L}} \frac{x_\ell y_\ell}{\lambda(\ell)}$ is, indeed, a scalar product.

... yields a simple quadratic program

The weights p^* that minimize the integrated square error for a given partition \mathcal{L} are given by the following:

Definition (Quadratic program)

p^* is the solution to the quadratic program :

$$\arg \min_{p \in \mathcal{C}_{\mathcal{L}}} \|p\|_{\mathcal{L}}^2 - 2 \langle p, f \rangle_{\mathcal{L}}$$

which is the projection of f onto $\mathcal{C}_{\mathcal{L}}$ regarding $\|\cdot\|_{\mathcal{L}}^2$.

We denote $p^* = P_{\mathcal{C}_{\mathcal{L}}}(f)$ this projection.

Note that without the constraints, $p^* = f$.

Joint optimisation fo the breakpoint and the weights

For a set of dimensions D in $\mathcal{P}(\{1, \dots, d\})$, let $L(\ell, x, D)$ be the partition of the leaf ℓ splitted on a point x in dimensions D , i.e:

$$L((a, b), x, D) = \times_{j \in D} \{(a_j, x_j], (x_j, b_j]\} \times \times_{j \in \{1, \dots, d\} \setminus D} \{(a_j, b_j]\}.$$

Define then the full partition by:

$$\mathcal{L}_{x,D} = \mathcal{L} \setminus \{\ell(x)\} \cup L(\ell(x), x, D).$$

We will omit the parameter D if $D = \{1, \dots, d\}$.

Definition (Final optimisation problem)

The global optimisation problem we want to solve is :

$$\begin{array}{l} \arg \min \\ D \in \mathcal{P}(\{1, \dots, d\}) \\ x \in \mathbb{I} \\ p \in \mathcal{C}_{\mathcal{L}_{x,D}} \end{array} \|p\|_{\mathcal{L}_{x,D}}^2 - 2 \langle p, f_{\mathcal{L}_{x,D}} \rangle_{\mathcal{L}_{x,D}}$$

The recursive procedure

1. Solve the *density* problem:

$$\arg \min_{\substack{D \in \mathcal{P}(\{1, \dots, d\}) \\ x \in \mathbb{I}}} -\|f_{\mathcal{L}_{x,D}}\|_{\mathcal{L}_{x,D}}^2$$

- Find the splitting dimensions D first
- Minimize greedily on x via a non-linear programming solver.

2. Recurse on each ℓ in $\mathcal{L}_{x,D}$ by rescaling ℓ to \mathbb{I} and solving the same problem to obtain the final partition \mathcal{L} .

3. Then, with \mathcal{L} fixed, solve the projection:

$$\arg \min_{p \in \mathcal{C}_{\mathcal{L}}} \|p\|_{\mathcal{L}}^2 - 2 \langle p, f_{\mathcal{L}} \rangle_{\mathcal{L}}$$

via a quadratic programming solver, with initial values $f_{\mathcal{L}}$.

Finding the splitting dimensions D (for $U \sim C$)

Hypothesis (\mathcal{H}_j)

$$(U_j \perp\!\!\!\perp U_{-j}) \mid U \in \ell \text{ and } U_j \mid U \in \ell \sim \mathcal{U}(\ell_j)$$

Bowman [2] : Suppose that $\ell = \mathbb{I}$, containing n obs. of the random variable $U \sim F$, for F the restriction of C to ℓ , rescaled to \mathbb{I} . Then:

Definition (Test statistic)

Denote by $f_{f, \mathcal{L}}^{(n)}$ the piecewise constant density that will be estimated on data $U_1, \dots, U_n \sim F$, and $e_{j,n}(x) = \mathbb{E}(f_{f, \mathcal{L}}^{(n)}(x) \mid \mathcal{H}_j)$.

The test statistic is given by :

$$\mathcal{I}_j = \|e_{j,n} - f_{f, \mathcal{L}}^{(n)}\|_2^2$$

where \mathcal{L} , $e_{j,n}$ and $f_{f, \mathcal{L}}^{(n)}$ are stochastic objects, depending on U .

Test procedure

We weakened the test by assuming that the next split is enough to test \mathcal{H}_j . This gives a test procedure as follows:

1. Solve

$$x^* = \arg \min_{x \in \mathbb{I}} -\|f_{\mathcal{L}_x}\|_{\mathcal{L}_x}^2$$

2. Compute:

$$\hat{\mathcal{I}}_j = \sum_{k \in \mathcal{L}_{x^*}, \{1, \dots, d\} \setminus \{j\}} \left(\frac{f_k^2}{\lambda(k)} + \sum_{\substack{\ell \in \mathcal{L}_{x^*}, \{1, \dots, d\} \\ \ell \subset k}} \left(\frac{f_\ell^2}{\lambda(\ell)} - 2 \frac{f_k f_\ell}{\lambda(k)} \right) \right).$$

Argument : the cut will be on the same x in dimensions other than j wheter or not we work under \mathcal{H}_j .

3. Compare to a Monte-carlo simulation of its distribution under the null to exclude the dimension j if necessary.

Asymptotic behavior

Previous result

Ram and Gray [4] gave the consistency of $f_{f,\mathcal{L}}^{(n)}$. Assuming the maximum diameter of leaves goes to 0 as n goes to ∞ , we have :

$$\mathbb{P} \left(\lim_{n \rightarrow +\infty} \|f_{f,\mathcal{L}}^{(n)} - f\|_2^2 = 0 \right) = 1.$$

Denoting q s.t:

$$\forall \ell \in \mathcal{L}, q_\ell = \int_{\ell} c(u) du,$$

this results writes $d_{\mathcal{L}}(f, q)^2 \rightarrow 0$, a.s.

Furthermore, by construction, $q \in \mathcal{C}$.

Constraint influence

Definition (Integrated constraint influence)

$$\|c_{p,\mathcal{L}}^{(n)} - f_{f,\mathcal{L}}^{(n)}\|_2^2 = d_{\mathcal{L}}(p, f)^2$$

This quantity measures how much f and p are far from each other. But since f is closer and closer to q , which is in the set that f is projected on to give p , we have :

Property (Asymptotical effect of constraints)

The integrated constraint influence is asymptotically 0.

Proof.

\mathcal{C} is convex, closed and non-empty. Hence $p = \mathcal{P}_{\mathcal{C}}(f)$ exist and is unique. Since $q \in \mathcal{C}$, we have that $d_{\mathcal{L}}(f, p)^2 \leq d_{\mathcal{L}}(f, q)^2$. \square

Property (Consistency)

For c the density of the true copula, assuming the diameter of the leaves goes to 0 as n goes to ∞ , the estimator $c_{p,\mathcal{L}}^{(n)}$ is consistent, i.e :

$$\mathbb{P} \left(\lim_{n \rightarrow +\infty} \|c_{p,\mathcal{L}}^{(n)} - c\|_2^2 = 0 \right) = 1$$

Proof.

$$\|c_{p,\mathcal{L}}^{(n)} - c\|_2^2 = d_{\mathcal{L}}(p, q)^2 \text{ and } d_{\mathcal{L}}(p, q)^2 \leq d_{\mathcal{L}}(f, q)^2. \quad \square$$

Bagging and cross-validation

A simple forest

In regression : See Breiman [3]

In density estimation, Kernels uses *leave-one-out* for bandwidths. Sain, Baggerly and Scot [5] formalized the cross-validation process for density estimation. The more involved *out-of-bag* procedure we propose is inspired by Wu [7].

Definition (Out-of-bag "density" and metrics)

$$c_{oob}(u) = \frac{1}{N(u)} \sum_{j=1}^N c^{(j)}(u) \mathbf{1}_{u \text{ was not in the training set of } c^{(j)}}$$

$$J_{oob}(c_N) = \|c_N\|_2^2 - \frac{2}{n} \sum_{i=1}^n c_{oob}(u_i)$$

$$KL_{oob}(c_N) = \int c(u) \ln \left(\frac{c(u)}{c_N(u)} \right) \approx -\frac{1}{n} \sum_{i=1}^n \ln(c_{oob}(x_i))$$

A weighted forest

After fitting the trees c^1, \dots, c^N , we can assign weights to them minimizing an out-of-bag integrated square error for the forest :

Definition (Out-of-bag "density" and metrics, weighted case)

$$c_{oob}^w(u) = \frac{1}{W(u)} \sum_{j=1}^N w_j c^{(j)}(u) \mathbf{1}_{u \text{ was not in the training set of } c^{(j)}}$$

Where $W(u)$ is the sum of w_j 's for trees that did not see u . Then :

Definition (Optimal weights)

$$w^* = \arg \min_w J_{oob}(c_N^w)$$

Simulation Study

- Simulation of 200 points from a 3-dimensional clayton copula with $\theta = 8$ for marginals 1, 3 and 4.
- The second marginal is added as independent uniform draws.
- The fourth marginal is flipped, inducing anticomonotonicity.

Marginals 1, 3 and 4 exhibit strong dependency.

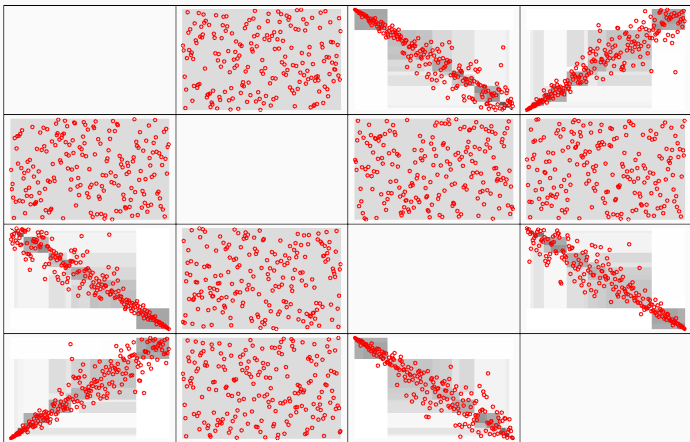


Figure 1: In gray scale, we observe a bivariate histogram of the simulation from the estimated tree. The small red points represent the input data.

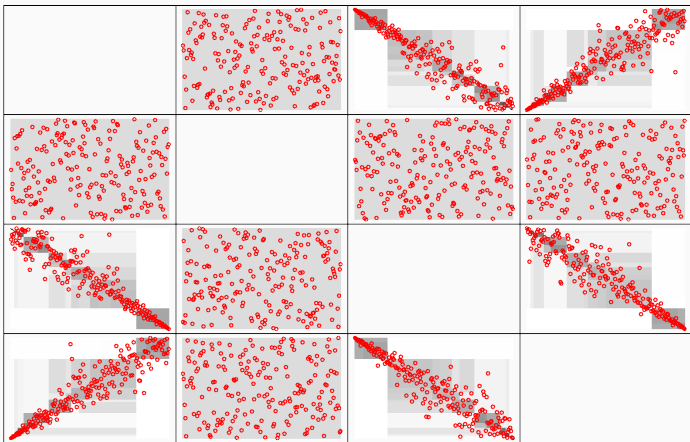


Figure 2: In gray scale, we observe bivariate simulations from the estimated tree without the localized dimension reduction. The small red points represent the data.

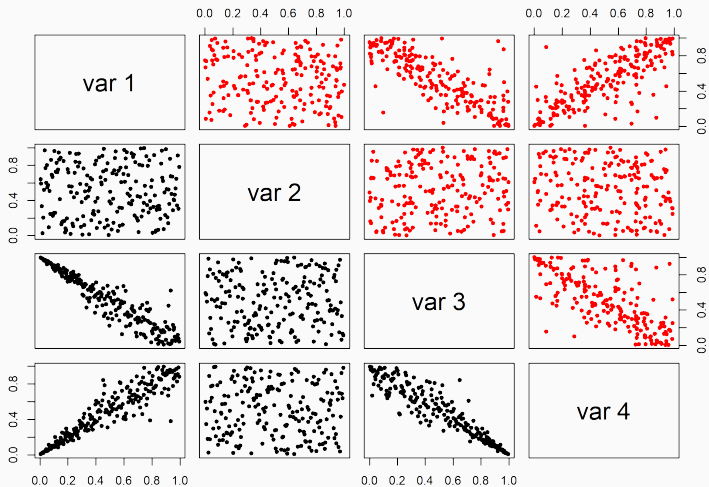


Figure 3: On the lower panel, in black, we observe the 200 inputted points. On the top panel, in red, we observe a simulation from the fitted forest with 500 trees.

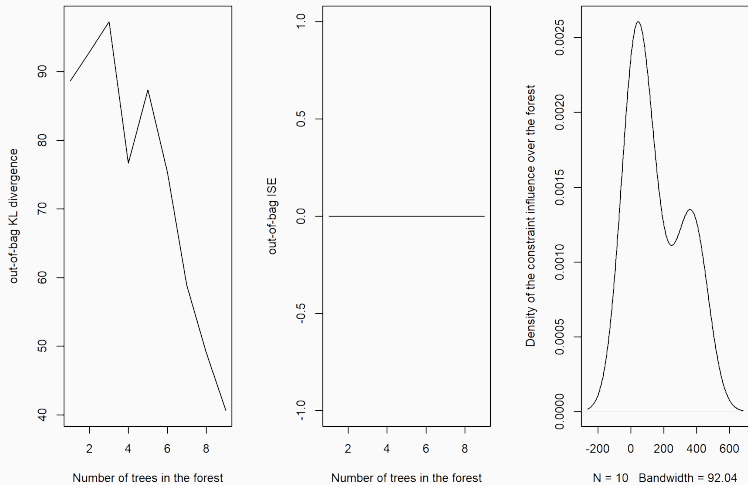


Figure 4: The kullback-leibler out-of-bag estimate is represented here in function of the number of trees already fitted in the forest.

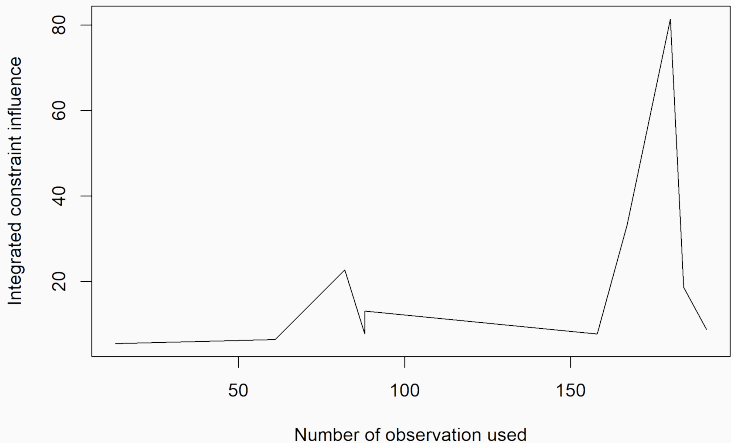


Figure 5: Integrated constraint influence of trees fitted on a subsample of increasing size of the dataset. The size of the subsample is in abscissa.

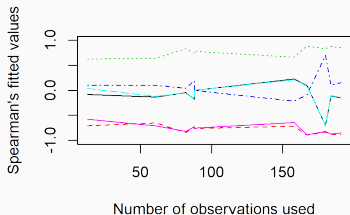
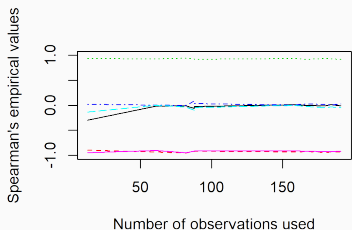
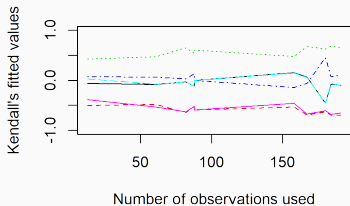
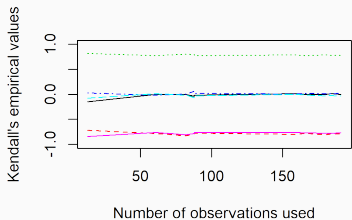


Figure 6: Top row: kendall's taus. Bottom row: Spearman's rho. Left: empirical values from burn-in data. Right : values from the fitted models. The size of the subsamples is in abssissa.

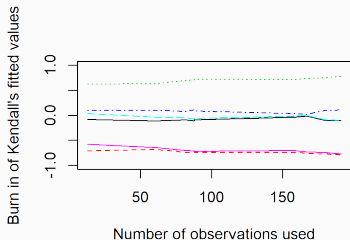
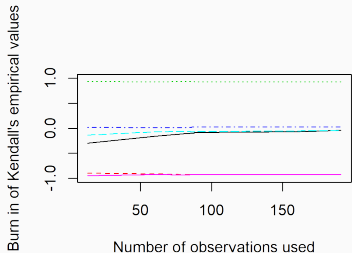
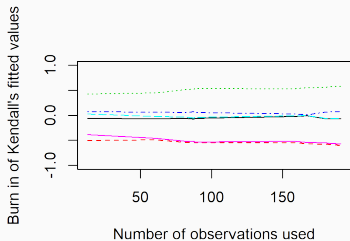
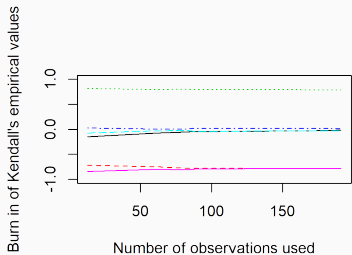


Figure 7: Burn-in of : Top row: kendall's taus. Bottom row: Spearman's rho. Left: empirical values from burn-in data. Right : values from the fitted models. The size of the subsamples is in abssissa.

Conclusion

Take away and potential improvements

Some take away points:

- Piecewise linear distribution function are handy models for copula modeling since the copula constraints have a nice expression
- Fitting piecewise linear d.f with trees is quite simple and fast
- The main issue is the degree of freedom in weights took away by the copula constraint.
- Such models can easily be bagged, boosted, cross-validated...

Some potential direction for future research:

- Higher-dimensionality ?
- Follow Biau [1] to initialise an autoencoder ?
- Efficiency of the current implementation ? (Python is slow)
- ...

References

G rard Biau, Erwan Scornet, and Johannes Welbl. “Neural Random Forests”. In: (Apr. 25, 2016).

A.W. Bowman. “Density Based Tests for Goodness-of-Fit”. In: *Journal of Statistical Computation and Simulation* 40.1-2 (Feb. 1992), pp. 1–13. ISSN: 0094-9655, 1563-5163.

Leo Breiman. “Out-of-Bag Estimation”. In: (1996), p. 13.

Parikshit Ram and Alexander G. Gray. “Density Estimation Trees”. In: *Proceedings of the 17th ACM SIGKDD International Conference on Knowledge Discovery and Data Mining - KDD '11*. The 17th ACM SIGKDD International Conference. San Diego, California, USA: ACM Press, 2011, p. 627. ISBN: 978-1-4503-0813-7.

Stephan R Sain, Keith A Baggerly, and David W Scott. “Cross-Validation of Multivariate Densities”. In: (1994), p. 12.

A Sklar. “Fonctions de Repartition   n Dimension et Leurs Marges”. In: *Universit  Paris* 8.3.2 (1959), pp. 1–3.

Kaiyuan Wu, Wei Hou, and Hongbo Yang. “Density Estimation via the Random Forest Method”. In: (2017), p. 28.